

when started

spin ArmMotor forward for 300 degrees ▶

broadcast Koe

repeat until Bumper8 pressed?

set drive velocity to 50 %

drive reverse

stop driving

drive reverse for 80 mm ▶

spin ArmMotor reverse for 300 degrees ▶

forever

wait 1 seconds

if Color detects blue green ? then

set TouchLED color to green

else

if Color detects blue ? then

set TouchLED color to blue

else

set TouchLED color to red

when I receive Koe

set TouchLED color to red violet